

Training Motion control tuning

This training starts on: 27-11-2019

Location: TU/e, Eindhoven
Price: 4.495,00 euro excl. VAT
Duration: 6 days in a period of 2 weeks
Contact: training@hightechinstitute.nl, +31 85 401 3600

Partner

Certified by

Euspen

Certification

This course is certified by the European society for precision engineering & nanotechnology (euspen) and the Dutch Society for Precision Engineering (DSPE) and leads to the ECP2-certificate.

Course leaders

Prof. Maarten Steinbuch
Dr. Ton van der Weiden

Teachers

Prof. Maarten Steinbuch
Dr. Ton van der Weiden
Michiel Vervoordeldonk MSc
Dr. Pieter Nuij
Dr. Tom Oomen
Frank Sperling MSc
Dr. Joost Bolder
Dr. Rick van der Maas
Dr. Marc van de Wal
Dr. Gert Witvoet
Tom Gommans MSc
Dr. Adrian Rankers
Dr. David Rijlaarsdam
Dr. Ewout van der Laan
Annemiek van der Maas - Rietschoten MSc
Dr. Michiel Beijen
Robert van der Weijst MSc
Dr. Rolf Gaasbeek
Enzo Evers MSc
Robin de Rozario MSc
Jurgen van Zundert MSc

Timetable

27-11-2019 | 09:00 - 17:00
28-11-2019 | 09:00 - 17:00
29-11-2019 | 09:00 - 17:00
02-12-2019 | 09:00 - 17:00
03-12-2019 | 09:00 - 17:00

Information is subject to change. Please contact High Tech Institute for the latest

Overview

The performance of controlled mechanical servosystems in an industrial setting is generally achieved by using PID controllers. In systems that suffer from dynamics and vibrations it is often useful to use additional filters, like notch-filters. The application of frequency domain techniques for analyzing requirements, describing controllers and carrying out experiments to find the optimal settings is very useful and will be treated during this course.

Starting with the time domain, the complete basis of control is repeated, placed in a modern framework, validated experimentally and applied to mechanical servo systems. During the course all aspects of 'motion control' are covered, including the use of feedforward steering.

After completion of the course you understand time and frequency techniques that are used in control and you are able to analyse industrial servo systems and determine proper settings for the controller. Next to tuning of the controller, you will be able to judge what the maximum performance is and which aspect is the limiting factor. Also you will gain practical experience with implementation and analysis instrumentation.

Intended for

This course focuses at engineers that are involved in controlled mechanical servo systems and want to gain more insight into the possibilities and limitations of servo control in an industrial setting.

Participants have a Bachelor or Master education in electrical engineering, mechanical engineering, mechatronics, physics or equivalent practical experience and need some basic understanding of servo control.

Programme

The course consists of a mixture of lectures, demonstrations, exercises and experiments. For the exercises a userfriendly Matlab application is used, whereas the experiments are performed with RTLinux based instrumentation.

The following topics are covered:

- Modelling of mechanical servo systems
- Time domain tuning
- Introduction frequency domain
- Stability
- Experimenting in the frequency domain
- Mechanical design for servo control
- Filters
- Design competition
- Design for performance
- Feedforward steering

- Digital control
- Interaction between control loops
- Robust and learning control